



# Application - Three-Phase Motors

## Reduced Voltage Starters

All Franklin three-phase submersible motors are suitable for full-voltage starting. Under this condition the motor speed goes from zero to full speed within a half second or less. The motor current goes from zero to locked rotor amps, then drops to running amps at full speed. This may dim lights, cause momentary voltage dips to other electrical equipment, and shock load power distribution transformers.

In some cases the power companies may require reduced-voltage starters to limit this voltage dip. There are also times when reduced-voltage starters may be desirable to reduce motor starting torque thus reducing the stress on shafts, couplings, and discharge piping. Reduced-voltage starters also slow the rapid acceleration of the water on start up to help control up thrust and water hammer.

Reduced-voltage starters may not be required if the maximum recommended cable length is used. With maximum recommended cable length there is a 5% voltage drop in the cable at running amps, resulting in about 20% reduction in starting current and about 36% reduction in starting torque compared to having rated voltage at the motor. This may be enough reduction in starting current so that reduced-voltage starters are not required.

**Three-Lead Motors:** Autotransformer or solid-state reduced-voltage starters may be used for soft-starting standard three-phase motors.

When autotransformer starters are used, the motor should be supplied with at least 55% of rated voltage to ensure adequate starting torque. Most autotransformer

starters have 65% and 80% taps. Setting the taps on these starters depends on the percentage of the maximum allowable cable length used in the system. If the cable length is less than 50% of the maximum allowable, either the 65% or the 80% taps may be used. When the cable length is more than 50% of allowable, the 80% tap should be used.

**Solid-state starters cannot be used with SubMonitor unless a bypass contactor is installed across the starter. Consult the factory for details.**

**Six-Lead Motors:** Wye-Delta starters are used with six-lead Wye-Delta motors. All Franklin 6" and 8" Three-phase motors are available in six-lead Wye-Delta construction. Consult the factory for details and availability. Part winding starters are not compatible with Franklin Electric submersible motors and should not be used.

Wye-Delta starters of the open-transition type, which momentarily interrupt power during the starting cycle, are not recommended. Closed-transition starters have no interruption of power during the start cycle and can be used with satisfactory results.

**Reduced-voltage starters have adjustable settings for acceleration ramp time, typically preset at 30 seconds. They must be adjusted so the motor is at full voltage within THREE SECONDS MAXIMUM to prevent excessive radial and thrust bearing wear.**

**If SubMonitor is used the acceleration time must be set to TWO SECONDS MAXIMUM due to the fast reaction time of the SubMonitor.**

## In-line Booster Pump Systems

Franklin Electric's submersible motors are acceptable for booster pumps, up to 93kW (125HP) motor shaft output, using an open or closed system flow sleeve provided the following conditions are taken into consideration in the system design.

### Design And Operational Requirements

- 1. Non-Vertical Operation:** Vertical Shaft-up (0°) to Horizontal (90°) operation is acceptable as long as the pump transmits "down-thrust" to the motor within 3 seconds after start-up and continuously during operation. However, it is best practice to provide a positive slope whenever it is possible, even if it is only a few degrees.
- 2. Motor, Sleeve, and Pump Support System:** The booster sleeve I.D. must be sized according to the motor cooling and pump NPSHR requirements. The support system must support the motor's weight, prevent motor rotation and keep the motor and pump aligned. The support system must also allow for thermal axial expansion of the motor without creating binding forces.
- 3. Motor Support Points:** A minimum of two support points are required on the motor. One in the motor/pump flange connection area and one in the bottom end of the motor area. The motor castings, not the shell area, are recommended as support points. If the support is a full length support and/or has bands in the shell area, they must not restrict heat transfer or deform the shell.
- 4. Motor Support Material and Design:** The support system should minimize turbulence, vibration, and flow restrictions. The support materials and locations must not inhibit the heat transfer away from the motor.
- 5. Motor and Pump Alignment:** The maximum allowable misalignment between the motor, pump, and pump discharge is 0.025 inch per 12 inches of length (2mm per 1000mm of length). This must be measured in both directions along the assembly using the motor/pump flange connection as the starting point. The booster sleeve and support system must be rigid enough to maintain this alignment during assembly, shipping, operation and maintenance.